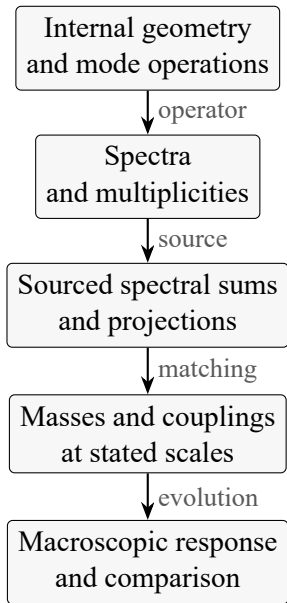
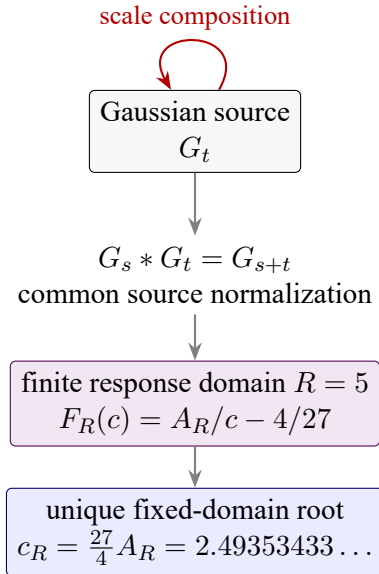


(1) Generated maps



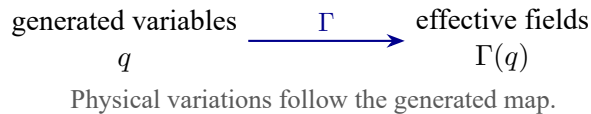
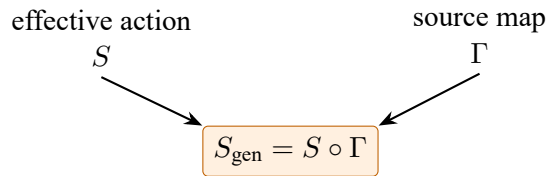
Each map retains its source, normalization and dependencies.

(2) Shared endpoint

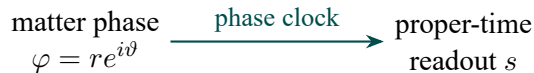


The same endpoint enters different physical readouts.

(3) Generated action and clock



Common source balance and constraint reduction



$$X = -(\nabla \vartheta)^2 > 0, \quad ds = d\vartheta / \sqrt{X}$$

Same occupied solution and macroscopic metric